

# A Dodecahedron - the 12-face Platonic Solid – 3D views, Datae, & the Source Code.

On pages ->

1 & 8

2, 3, & 7

4 & 5

- The vertices fit inside a sphere of radius=1. with geometry control based on using:

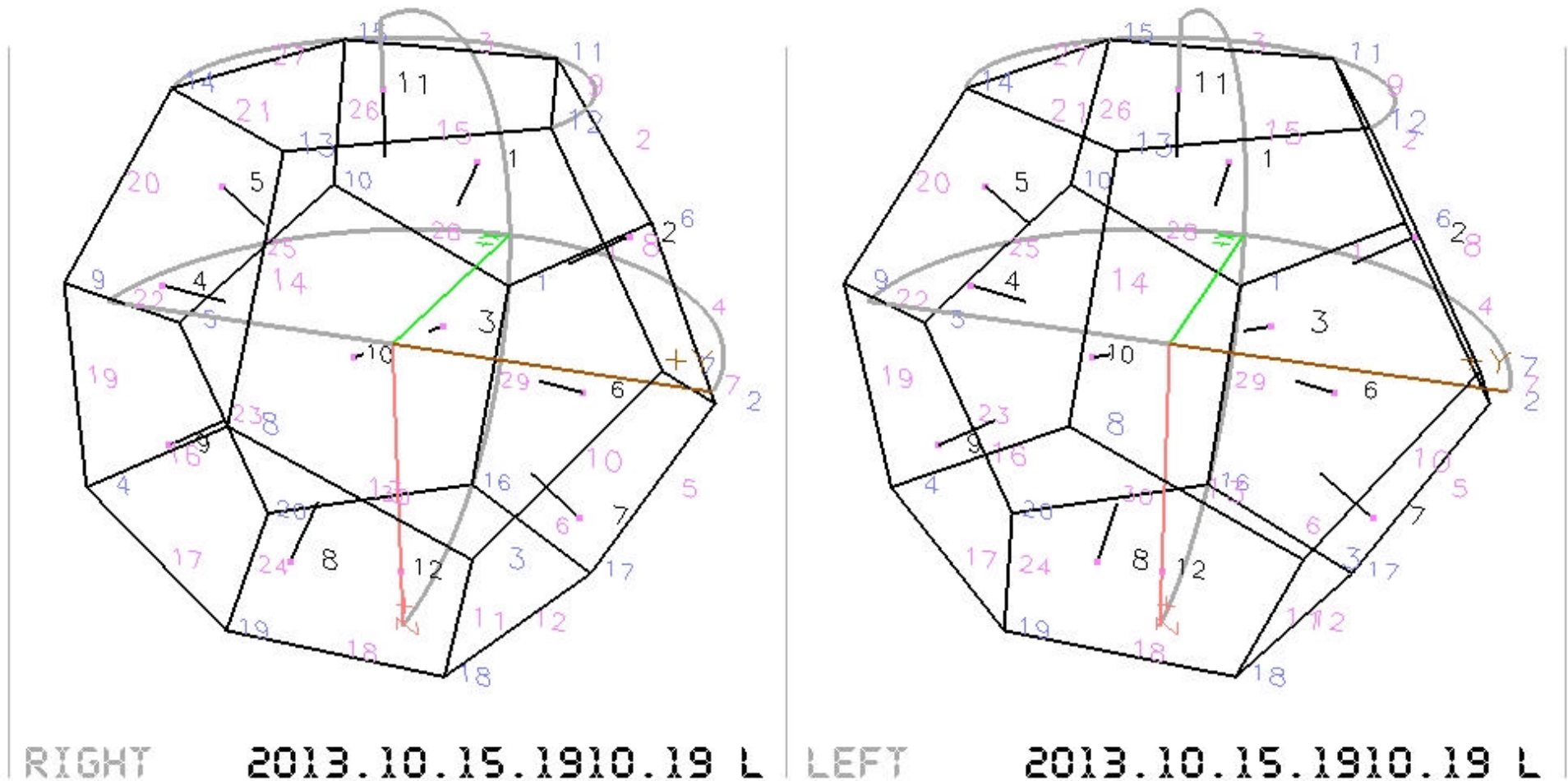
Vertex #1 pitch angle = -10.81231696357170629128494477447210\_16 degrees

Vertex #16 pitch angle = -52.62263185935030435714286150500714\_16 degrees

- The resulting vertices are regularly-spaced to the accuracy shown on page two.

- My reference: Wikipedia's in-depth article: "Dodecahedron". Theoretical values: see pages 6 & 7.

## A crossed-eye 3D visualization of the "Setterholm Model" orientation & indices:



See also: <http://ftp.setterholm.com/Fortran/Dodec-3D-RightLeft.jpg>

## The “Setterholm Model” indices:

Face:	CCW looking out Vertex Index	Vertex:	CCW looking out FaceIndex	Edge:VertexIndex &	ComputedLength	
# 1=(	1, 6, 11, 15, 10/)	# 1=(	1, 10, 6/)	# 1=(	1, 6/)	: 0. 71364417954617986388393968609267
# 2=(	2, 7, 12, 11, 6/)	# 2=(	2, 6, 7/)	# 2=(	6, 11/)	: 0. 71364417954617986388393968609216
# 3=(	3, 8, 13, 12, 7/)	# 3=(	3, 7, 8/)	# 3=(	11, 15/)	: 0. 71364417954617986388393968609288
# 4=(	4, 9, 14, 13, 8/)	# 4=(	4, 8, 9/)	# 4=(	6, 2/)	: 0. 71364417954617986388393968609264
# 5=(	5, 10, 15, 14, 9/)	# 5=(	5, 9, 10/)	# 5=(	2, 17/)	: 0. 71364417954617986388393968609216
# 6=(	6, 1, 16, 17, 2/)	# 6=(	6, 2, 1/)	# 6=(	17, 16/)	: 0. 71364417954617986388393968609283
# 7=(	7, 2, 17, 18, 3/)	# 7=(	7, 3, 2/)	# 7=(	2, 7/)	: 0. 71364417954617986388393968609014
# 8=(	8, 3, 18, 19, 4/)	# 8=(	8, 4, 3/)	# 8=(	7, 12/)	: 0. 71364417954617986388393968609216
# 9=(	9, 4, 19, 20, 5/)	# 9=(	9, 5, 4/)	# 9=(	12, 11/)	: 0. 71364417954617986388393968609128
#10=(	10, 5, 20, 16, 1/)	#10=(	10, 1, 5/)	#10=(	7, 3/)	: 0. 71364417954617986388393968609264
#11=(	13, 14, 15, 11, 12/)	#11=(	1, 2, 11/)	#11=(	3, 18/)	: 0. 71364417954617986388393968609215
#12=(	19, 18, 17, 16, 20/)	#12=(	2, 3, 11/)	#12=(	18, 17/)	: 0. 71364417954617986388393968609126
		#13=(	3, 4, 11/)	#13=(	3, 8/)	: 0. 71364417954617986388393968609266
		#14=(	4, 5, 11/)	#14=(	8, 13/)	: 0. 71364417954617986388393968609215
		#15=(	5, 1, 11/)	#15=(	13, 12/)	: 0. 71364417954617986388393968609283
		#16=(	6, 10, 12/)	#16=(	8, 4/)	: 0. 71364417954617986388393968609264
		#17=(	7, 6, 12/)	#17=(	4, 19/)	: 0. 71364417954617986388393968609215
		#18=(	8, 7, 12/)	#18=(	19, 18/)	: 0. 71364417954617986388393968609283
		#19=(	9, 8, 12/)	#19=(	4, 9/)	: 0. 71364417954617986388393968609267
		#20=(	10, 9, 12/)	#20=(	9, 14/)	: 0. 71364417954617986388393968609216
				#21=(	14, 13/)	: 0. 71364417954617986388393968609282
				#22=(	9, 5/)	: 0. 71364417954617986388393968609012
				#23=(	5, 20/)	: 0. 71364417954617986388393968609215
				#24=(	20, 19/)	: 0. 71364417954617986388393968609127
				#25=(	5, 10/)	: 0. 71364417954617986388393968609266
				#26=(	10, 15/)	: 0. 71364417954617986388393968609215
				#27=(	15, 14/)	: 0. 71364417954617986388393968609126
				#28=(	10, 1/)	: 0. 71364417954617986388393968609275
				#29=(	1, 16/)	: 0. 71364417954617986388393968609215
				#30=(	16, 20/)	: 0. 71364417954617986388393968609290

Theoretical Edge Length= 0. 71364417954617986388393968609217  
 =(sqrt(5.) - 1.) / sqrt(3.)

RMS Error =  $\frac{1}{12345678901234567890123456789012} - \frac{2}{1234567890123456789012} - \frac{3}{1234567890123456789012}$   
 0. 737926D- 30 : ^

Here:  
 real\*16 precision = 31 significant digits  
 & printouts are often zeros beyond ~ 34.

# The "Setterholm Model" coordinates - version 1.0:

Vertices:	X	Y	Z
1*=(/	0. 982246946376846022815670275235,	0. 00000000000000000000000000000000,	0. 187592474085079899860139346908/)
2 =(/	0. 303530999103343111547695790709,	0. 934172358962715696451118623548,	0. 187592474085079899860139346908/)
3 =(/	-0. 794654472291766122955530928327,	0. 577350269189625764509148780503,	0. 187592474085079899860139346908/)
4 =(/	-0. 794654472291766122955530928327,	-0. 577350269189625764509148780502,	0. 187592474085079899860139346908/)
5 =(/	0. 303530999103343111547695790709,	-0. 934172358962715696451118623548,	0. 187592474085079899860139346908/)
6 =(/	0. 794654472291766122955530928327,	0. 577350269189625764509148780502,	-0. 187592474085079899860139346908/)
7 =(/	-0. 303530999103343111547695790709,	0. 934172358962715696451118623548,	-0. 187592474085079899860139346908/)
8 =(/	-0. 982246946376846022815670275235,	0. 00000000000000000000000000000000,	-0. 187592474085079899860139346908/)
9 =(/	-0. 303530999103343111547695790709,	-0. 934172358962715696451118623548,	-0. 187592474085079899860139346908/)
10 =(/	0. 794654472291766122955530928327,	-0. 577350269189625764509148780503,	-0. 187592474085079899860139346908/)
11 =(/	0. 491123473188423011407835137617,	0. 356822089773089931941969843046,	-0. 794654472291766122955530928328/)
12 =(/	-0. 187592474085079899860139346907,	0. 577350269189625764509148780502,	-0. 794654472291766122955530928328/)
13 =(/	-0. 607061998206686223095391581420,	0. 00000000000000000000000000000000,	-0. 794654472291766122955530928328/)
14 =(/	-0. 187592474085079899860139346907,	-0. 577350269189625764509148780502,	-0. 794654472291766122955530928328/)
15 =(/	0. 491123473188423011407835137617,	-0. 356822089773089931941969843046,	-0. 794654472291766122955530928328/)
16*=(/	0. 607061998206686223095391581420,	0. 00000000000000000000000000000000,	0. 794654472291766122955530928328/)
17 =(/	0. 187592474085079899860139346907,	0. 577350269189625764509148780502,	0. 794654472291766122955530928328/)
18 =(/	-0. 491123473188423011407835137617,	0. 356822089773089931941969843046,	0. 794654472291766122955530928328/)
19 =(/	-0. 491123473188423011407835137617,	-0. 356822089773089931941969843046,	0. 794654472291766122955530928328/)
20 =(/	0. 187592474085079899860139346907,	-0. 577350269189625764509148780502,	0. 794654472291766122955530928328/)

Face normals:	X	Y	Z
1 =(/	0. 710760567467444858308480481425,	0. 00000000000000000000000000000000,	-0. 355380283733722429154240240713/)
2 =(/	0. 219637094279021846900645343808,	0. 675973469215554570772500930230,	-0. 355380283733722429154240240713/)
3 =(/	-0. 575017378012744276054885584520,	0. 417774579468393445093883236911,	-0. 355380283733722429154240240713/)
4 =(/	-0. 575017378012744276054885584520,	-0. 417774579468393445093883236911,	-0. 355380283733722429154240240713/)
5 =(/	0. 219637094279021846900645343807,	-0. 675973469215554570772500930230,	-0. 355380283733722429154240240713/)
6 =(/	0. 575017378012744276054885584520,	0. 417774579468393445093883236911,	0. 355380283733722429154240240713/)
7 =(/	-0. 219637094279021846900645343808,	0. 675973469215554570772500930230,	0. 355380283733722429154240240713/)
8 =(/	-0. 710760567467444858308480481425,	0. 00000000000000000000000000000000,	0. 355380283733722429154240240713/)
9 =(/	-0. 219637094279021846900645343808,	-0. 675973469215554570772500930230,	0. 355380283733722429154240240713/)
10 =(/	0. 575017378012744276054885584520,	-0. 417774579468393445093883236911,	0. 355380283733722429154240240713/)
11 =(/	0. 00000000000000000000000000000000,	0. 00000000000000000000000000000000,	-0. 794654472291766122955530928328/)
12 =(/	-0. 00000000000000000000000000000000,	0. 00000000000000000000000000000000,	0. 794654472291766122955530928328/)

Web Link to this document: <http://ftp.setterholm.com/Fortran/Dodec.pdf>

Because no one is perfect, and *lawyers* abound: recognize that this is simply "my best shot... as of today".

The software, data, images, and documentation here are provided "as is", without guarantees or warranties of any kind, either expressed or implied, including, but not limited to, fitness for any particular purpose.

Subroutine DodecModel16(iP)

```
!2013. 10. 15. 2200cdt JMS- Dodecahedron - the 12-face Platonic Solid
! which fits inside a sphere of radius=1.0
! Traveler2/Athlon64/WInXPPro/APF9.0/Ogl1.2.1
!-----
! Reference: Wikipedia's article on "Dodecahedron".
implicit none
!-----
!----- Arguments
integer*4::iP
!----- Internals
!type:: DodecRec ;sequence
integer*4::Init
!Theoretical value:
real*16 ::EdgeL !Edge length =(sqrt(5.)-1.)/sqrt(3.)
!My model parameters:
real*16 :: v1Ang !Vertex - #1- Pitch Angle w.r.t. the X-Y plane.
real*16 :: v16Ang ! - #16-
!Indices:
integer*4::iFace(5, 12) !Face - vertex # list (CCW looking out)
integer*4::iEdge(2, 30) !Edge - vertex # list
integer*4::iVertex(3, 20) !vertex - vNormal # list (CCW looking out)
!Computed Vertices & Normals
!Note: I use homogeneous vectors, but you can ignore the 4th component here.
real*16 ::Vertex(4, 20) ! Vertex vector (X, Y, Z, 1.)
real*16 ::vNormal(4, 12) !Face normal vector (X, Y, Z, 1.)
real*16 ::EdgeLength(30) !Edge- lengths- ~= EdgeL ...Yes!
real*16 ::EdgeLErrorRms ! - RMS error
!end type DodecRec ;type(DodecRec)::Dd16
!-- Internal use variables
integer*4::i, iDel, iDel2, j
real*16 ::v0=0._16 !0.
real*16 ::v1=1._16 !1.
real*16 ::Angle !Yaw angle-
real*16 ::Ver1(4) !Vertex vector- # 1- used as a template (X, Y, Z, 1.)
real*16 ::Ver16(4) ! - #16- (X, Y, Z, 1.)
real*16 ::sY, cY !Yaw - cosine, sine
real*16 ::sP, cP !Pitch- cosine, sine
real*16 ::vTemp(4) !Temporary vector (X, Y, Z, 1.)

!----- Dodecahedron initialization - Jeff Setterholm's algorithm:
if(Init.eq.0) then
!----
EdgeL =(sqrt(5._16)-1._16)/sqrt(3._16) !Theoretical value.
! = 0.713644179546179863883939686092_16
V1Ang =- 10.81231696357170629128494477447230_16 !=Pitch angle v#1
V16Ang=- 52.62263185935030435714286150500763_16 !=Pitch angle v#16

!-- Index faces & edges:
iDel =5 ; iDel2=0
do i=1, 5 !Index faces(10 of 12 sets) {-CCW looking out} & all edges(30):
iFace(1:5, i )=(/i , i+5, i+10, i+ 9+iDel , i+4+iDel /) !Face[ 1, 5]
iFace(1:5, i +5)=(/i+5, i , i+15, i+16-iDel2, i+1-iDel2/) !Face[ 6, 10]
iEdge(1:2, i*6-5)= iFace(1:2, i) !Edge(1, 7, 13, 19, 25)
iEdge(1:2, i*6-4)= iFace(2:3, i) !Edge(2, 8, 14, 20, 26)
iEdge(1:2, i*6-3)= iFace(3:4, i) !Edge(3, 9, 15, 21, 27)
iEdge(1:2, i*6-2)=(/iFace(1, i+5), iFace(5, i+5) /) !Edge(4, 10, 16, 22, 28)
iEdge(1:2, i*6-1)=(/iFace(5, i+5), iFace(4, i+5) /) !Edge(5, 11, 17, 23, 29)
iEdge(1:2, i*6 )=(/iFace(4, i+5), iFace(3, i+5) /) !Edge(6, 12, 18, 24, 30)
iVertex(1:3, i )=(/i , i+4+iDel , i+5/) !iVertex[ 1, 5]
iVertex(1:3, i +5)=(/i+5, i+1-iDel2, i /) !iVertex[ 6, 10]
iVertex(1:3, i +10)=(/i , i+1-iDel2, 11/) !iVertex[11, 15]
iVertex(1:3, i +15)=(/i+5, i+4+iDel , 12/) !iVertex[16, 20]
if(i.eq.1) iDel =0
if(i.eq.4) iDel2=5
enddo!i
iFace( 1:5, 11)=(/13, 14, 15, 11, 12/) !Face #11-Top
iFace( 1:5, 12)=(/19, 18, 17, 16, 20/) !Face #12-Bottom
Init=1
endif !Init=0
```

```

!----- From here on: V1Ang & V16Ang quantify the model...
!-- Setup the Vertex templates:
call SinCos16(v1Ang , sP, cP) ;Ver1 =(/cP, v0, -sP, v1/) != vertex#1
call SinCos16(v16Ang, sP, cP) ;Ver16=(/cP, v0, -sP, v1/) != vertex#16
do i=1, 5 !-- Yaw the two vertex templates to define all the vertices:
  Angle=(i - 1)*72. _16 ; call SinCos16(Angle, sY, cY)
  Vertex( 1: 4, i )=(/ Ver1(1)*cY, Ver1(1)*sY, Ver1(3), v1/)!Ver[ 1, 5]
  Vertex(1: 4, i+15)=(/Ver16(1)*cY, Ver16(1)*sY, Ver16(3), v1/)!Ver[16, 20]
  Angle=(i - 1)*72. _16+36. _16 ; call SinCos16(Angle, sY, cY)
  Vertex( 1: 4, i+5)=(/ Ver1(1)*cY, Ver1(1)*sY, -Ver1(3), v1/)!Ver[ 6, 10]
  Vertex(1: 4, i+10)=(/Ver16(1)*cY, Ver16(1)*sY, -Ver16(3), v1/)!Ver[11, 15]
enddo!i

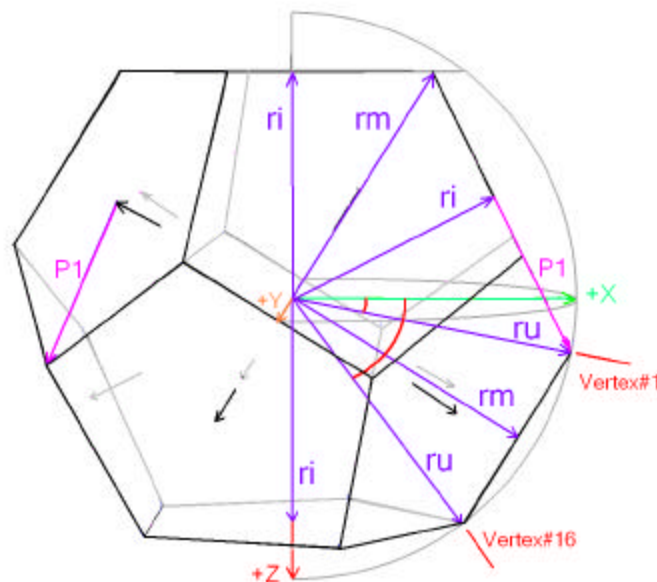
!-- Compute each Face Normal vector by averaging its five vertices:
do i=1, 12 ; vNormal (1: 4, i)=0. _16
  do j=1, 5 ; vNormal (1: 4, i)=vNormal (1: 4, i)+Vertex(1: 4, iFace(j, i)); enddo!j
  vNormal (1: 4, i)=vNormal (1: 4, i)/5. _16
enddo!i

!-- Compute the resulting Edge Lengths:
EdgeLErrorRms=0. _16
do i=1, 30
  vTemph=Vertex(1: 4, iEdge(2, i))-Vertex(1: 4, iEdge(1, i))
  EdgeLength(i)= &
    vTemph(1)*vTemph(1)+vTemph(2)*vTemph(2)+vTemph(3)*vTemph(3)
  call Sqrt16(EdgeLength(i), EdgeLength(i), 0)
  EdgeLErrorRms=EdgeLErrorRms+(EdgeLength(i) - EdgeL)*(EdgeLength(i) - EdgeL)
enddo!i
EdgeLErrorRms=EdgeLErrorRms/30. _16
call Sqrt16(EdgeLErrorRms, EdgeLErrorRms, 0)

!----- Report the results:
if(iP. gt. 5) then
  write(iP, "(f36. 32, ' = V#1 pitch angle' )") v1Ang
  write(iP, "(f36. 32, ' = V#16 pitch angle' )") v16Ang
  write(iP, ("/' Vertices: ' )")
  do i=1, 20
    write(iP, "(i2, ' =( /, 2(f34. 30, ' , ' ), f34. 30, ' /)' )") i, Vertex( 1: 3, i)
  enddo!i
  write(iP, ("/' Face normals: ' )")
  do i=1, 12
    write(iP, "(i2, ' =( /, 2(f34. 30, ' , ' ), f34. 30, ' /)' )") i, vNormal ( 1: 3, i)
  enddo!i
  !-- Indices & Lengths:
  write(iP, ("/' CCW looking out CCW looking out' )")
  write(iP, "( ' Face: VertexIndex Vertex: FaceIndex ' \)")
  write(iP, "( ' Edge: VertexIndex & ComputedLength' )")
  do i=1, 30 ! ...print in three side-by-side columns...
    if(i. le. 12) then
      write(iP, "( ' #', i2, ' =( ' , 4(i2, ' , ' ), i2, ' /)' \)") i, iFace(1: 5, i)
    else; write(iP, "( ' ' \)")
    endif !i<=12
    if(i. le. 20) then
      write(iP, "( ' #', i2, ' =( ' , 2(i2, ' , ' ), i2, ' /)' \)") i, iVertex(1: 3, i)
    else; write(iP, "( ' ' \)")
    endif !i<=20
    write(iP, "( ' #', i2, ' =( ' , 1(i2, ' , ' ), i2, ' /)' \)") i, iEdge(1: 2, i)
    write(iP, "( ' :', f35. 32) ) EdgeLength(i)
  enddo!i
  write(iP, ("/36x, ' Theoretical Edge Length=', f35. 32) ) EdgeL
  write(iP, "( 72x, ' 1 2 3' )")
  write(iP, "( 63x, ' 12345678901234567890123456789012' )")
  write(iP, "( 67x, ' RMS Error=', d13. 6, ' : ^' )") EdgeLErrorRms
endif !iP>5
return
End Subroutine DodecModel 16

```

Relating my model to Wikipedia's exact model :



Define the radii of three spheres:

**ru** = the circumscribing (outside) sphere touching all 20 vertices:

$$= (1 + \sqrt{5}) * \sqrt{3} / 4$$

@ 1. 40125853844407354467667793532207

**rm** = the sphere tangent to the middle of all 30 edges:

$$= (\sqrt{5} + 3) / 4$$

@ 1. 30901699437494742410229341718282

**ri** = the sphere tangent to the center of all 12 faces:

$$= (\sqrt{\sqrt{5} * 11/10 + 5/2}) / 2$$

@ 1. 11351636441160673519437503948696

**P1** = radius of the circle touching the five vertices of each face"

$$= \sqrt{ru * ru - ri * ri}$$

@ 0. 85065080835203993218154049706302

The theoretical value of my model parameters become:

$$\sin V1Ang = (ri - 2 * P1) / (ru * \sqrt{5})$$

@ -0. 18759247408507989986013934690761

$$V1Ang = \arcsine(\sin V1Ang)$$

V1Ang @ -10. 81231696357170629128494477447353 degrees

- and -

$$\cos V16Ang = P1 / ru$$

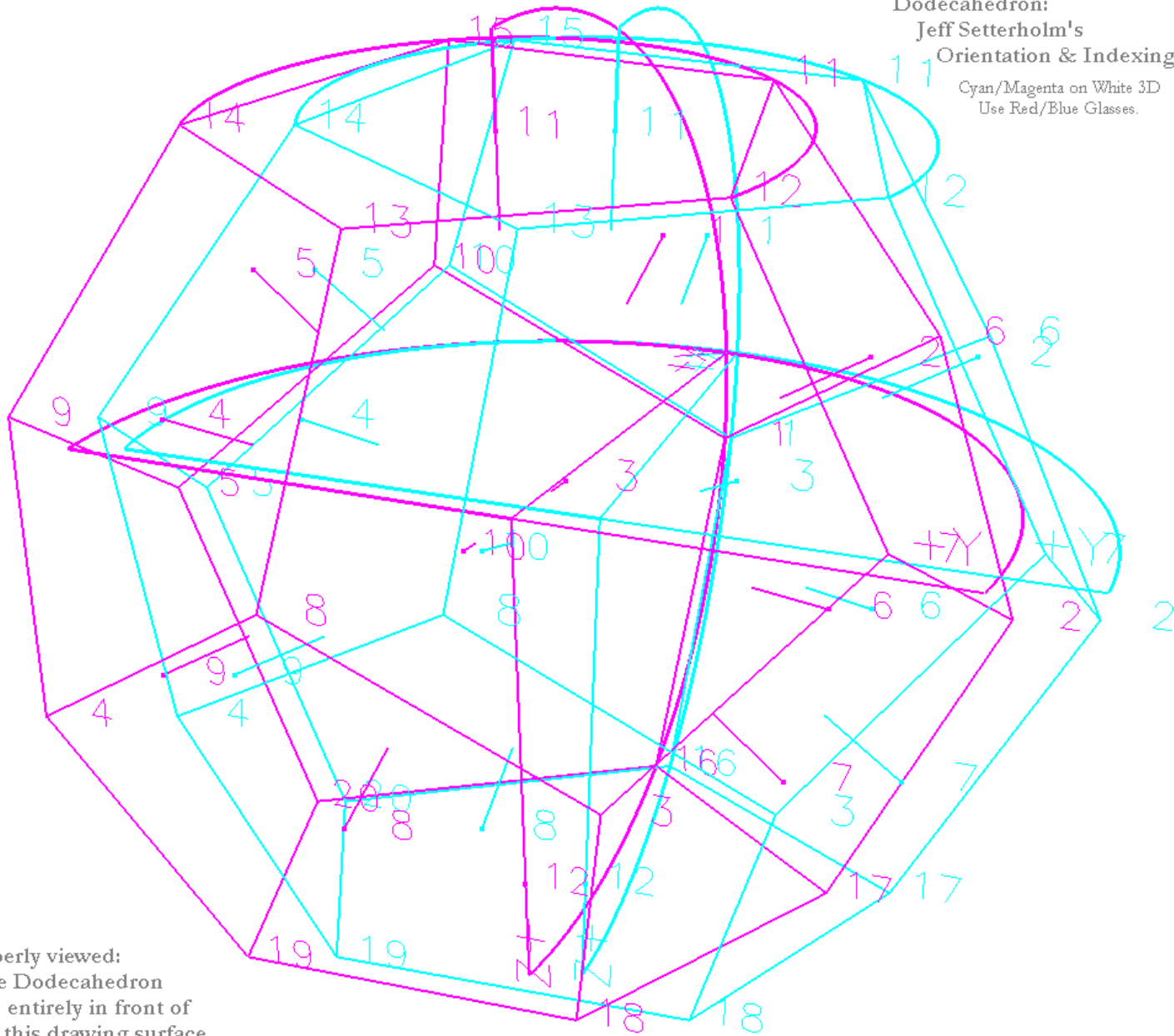
@ 0. 60706199820668622309539158141999

$$V16Ang = - \arccosine(\cos V16Ang)$$

V16Ang @ -52. 62263185935030435714286150510032 degrees



Dodecahedron:  
 Jeff Setterholm's  
 Orientation & Indexing  
 Cyan/Magenta on White 3D  
 Use Red/Blue Glasses.



Properly viewed:  
 The Dodecahedron  
 is entirely in front of  
 this drawing surface.

2013.10.15.0800.30 L